

Affine Motion in a Finsler Space with Non-Symmetric Connections

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Abstract

Takano [5] studied the affine motion and its properties in a recurrent Finsler space. Further, Pandey and Tiwari [3] developed the existence of affine motion in a $R - \oplus$ recurrent Finsler space equipped with non-symmetric connections. The object of the present paper is to study the infinitesimal affine motion $\bar{x}^i = x^i + v^i(x)$ dt in a Finsler space with non-symmetric connection. Some useful investigation have been obtained in the paper.

Keywords : Affine motion, Non-symmetric connection, Covariant derivative.

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1. Introduction

Consider an n-dimensional Finsler space F_n , [4] having $2n$ -line elements $(x, \dot{x})$ equipped with non-symmetric connection $\Gamma_{jk}^i(x, \dot{x})$ (i, j etc. = 1, 2, 3, ..., n). The non-symmetric connection Γ_{jk}^i is based on non-symmetric fundamental metric tensor $g_{ij}(x, \dot{x}) \neq g_{ji}(x, \dot{x})$. Also the non-symmetric connection Γ_{jk}^i is homogeneous of degree zero in its directional arguments $\dot{x}$. Here, the non-symmetric connection Γ_{jk}^i can be written as :

$$\Gamma_{jk}^i = M_{jk}^i(x, \dot{x}) + \frac{1}{2} N_{jk}^i(x, \dot{x}), [1] \quad (1.1)$$

where M_{jk}^i and $\frac{1}{2} N_{jk}^i$ denote symmetric and skew-symmetric parts of Γ_{jk}^i respectively.

The covariant derivative of a tensor field $T_j^i(x, \dot{x})$ with respect to x^k are defined in two ways : [2]

$$T_{j \mid k}^i = \partial_k T_j^i - (\partial_m T_j^i) \Gamma_{pk}^m \dot{x}^p + T_j^m \Gamma_{mk}^i - T_m^i \Gamma_{jk}^m \quad (1.2)$$

$$T_{j \mid k}^i = \partial_k T_j^i - (\partial_m T_j^i) \hat{\Gamma}_{pk}^m \dot{x}^p + T_j^m \hat{\Gamma}_{mk}^i - T_m^i \Gamma_{jk}^m, \quad (1.3)$$

where $\hat{\Gamma}_{jk}^i = \Gamma_{kj}^i$.

The covariant derivative defined by (1.2) is called $\oplus$ -covariant derivative while defined by (1.3) is called $\ominus$ -covariant derivative.

The commutation formula involving $\oplus$ -covariant derivative for a tensor T_j^i is given by

$$T_{j \mid hk}^i - T_{j \mid kh}^i = (\partial_m T_j^i) R_{hk}^m + T_j^m R_{mhk}^i - T_m^i R_{jhk}^m + T_{j \mid m}^i N_{kj}^m, \quad [3] \quad (1.4)$$

where

$$R_{hjk}^i = \partial_k \Gamma_{hj}^i - \partial_j \Gamma_{hk}^i + (\partial_m \Gamma_{hj}^i) \Gamma_{sk}^m \dot{x}^s - (\partial_m \Gamma_{hk}^i) \Gamma_{sj}^m \dot{x}^s + \Gamma_{hj}^p \Gamma_{pk}^i - \Gamma_{hk}^p \Gamma_{pj}^i, \quad (1.5)$$

is called relative curvature tensor field and satisfies the following identities : [3]

$$\begin{aligned} (a) \quad R_{hjk}^i &= -R_{hkj}^i \\ (b) \quad R_{hjl}^i &= R_{hj}^i. \end{aligned} \quad (1.6)$$

Let us consider an infinitesimal point transformation

$$x^{-i} = x^i + v^i(x) dt, \quad [4] \quad (1.7)$$

where $v^i(x)$ be a vector field and dt an infinitesimal point constant.

In view of transformation (1.7) and covariant derivative defined by (1.4) and (1.5), the Lie derivative of $T_j^i(x, \dot{x})$ and $\Gamma_{jk}^i(x, \dot{x})$ are defined as : [3]

$$L_V T_j^i = T_{j \mid h}^i v^h - T_j^h V_{\mid h}^i + T_h^i V_{\mid j}^h + \partial_h T_j^i V_{\mid s}^h \dot{x}^s \quad (1.8)$$

$$L_V \Gamma_{jk}^i = V_{Ij}^i + R_{jkh}^i V^h + \partial_r \Gamma_{jk}^i V_{Is}^r \dot{x}^s. \quad (1.9)$$

The Lie-derivation of the curvature tensor R_{jkh}^i may be given by

$$\begin{aligned} L_V R_{hjk}^i &= R_{hjk}^i + V_{Ih}^s + R_{sjk}^i V_{Ih}^s + R_{hsk}^i V_{Ij}^s + R_{hjk}^i V_{Ik}^s \\ &\quad - R_{hjk}^i V_{Is}^s + \partial_r R_{hjk}^i V_{Is}^r \dot{x}^s. \end{aligned} \quad (1.10)$$

With the help of (1.9), (1.10) and covariant derivatives defined in (1.2) and (1.3), we have following two commutation formula

$$\begin{aligned} (L_V T_{jk}^i)_{+I s} - L_V (T_{jk}^i + V_{Is}^i) &= T_{mk}^i (L_V \Gamma_{js}^m) + \Gamma_{jm}^i (L_V \Gamma_{ks}^m) - T_{jk}^m (L_V \Gamma_{ms}^i) \\ &\quad + \partial_m T_{jk}^i (L_V \Gamma_{rs}^m) \dot{x}^r. \end{aligned} \quad (1.11)$$

$$\begin{aligned} (L_V \Gamma_{jh}^i)_{+I k} - (L_V \Gamma_{kh}^i)_{+I j} &= L_V R_{hjk}^i + \partial_r \Gamma_{jh}^i (L_V \Gamma_{ks}^r) \dot{x}^s - \partial_r \Gamma_{hk}^i (L_V \Gamma_{js}^r) \dot{x}^s. \end{aligned} \quad (1.12)$$

We shall use following results : [2]

$$\begin{aligned} (a) \quad \dot{x}_{+I k}^i &= 0. \\ (b) \quad \dot{x}_{I k}^i &= 0. \end{aligned} \quad (1.13)$$

2. Discussion

In order that the transformation (1.7) considered at each point of the space is infinitesimal affine motion if and only if

$$L_V \Gamma_{jk}^i = 0, [6]. \quad (2.1)$$

Introducing the result (2.1) in commutation formula (1.12), we find

$$L_V R_{hjk}^i = 0. \quad (2.2)$$

Thus, we have

Theorem (2.1). In a Finsler space F_n with non-symmetric connection admitting affine motion, the curvature tensor R_{hjk}^h becomes a Lie-invariant.

Now, applying the condition (2.1) in relation (1.11), we get

$$\left(L_V T_{jk}^i \right)_{I s} - L_V (T_{jk I s}^i) = 0. \quad (2.3)$$

Therefore, we have

Theorem (2.2). In a Finsler space F_n with non-symmetric connection admitting affine motion, the tensor field T_j^i satisfies the differential equation (2.3).

Let us suppose that vector V^i be parallel in F_n admitting an affine motion.

Then, we have

$$V_{I j}^i = 0. \quad (2.4)$$

From equations (1.10), (2.2) and (2.4), we get following useful result

$$R_{j h k I s}^i + V^s = 0. \quad (2.5)$$

Theorem (2.3). If the vector V^i be parallel in a Finsler space with non-symmetric connection admitting an affine motion, then conditions (2.5) holds.

Applying condition (2.1) in (1.9), we get

$$V_{I j I k}^i + R_{j k h}^i V^h + \partial_I \Gamma_{j k}^i V_{I s}^r \dot{x}^s = 0. \quad (2.6)$$

Suppose the vector V^{is} is parallel in F_n , then relation (2.4) will hold and consequently the equation (2.6) yields

$$R_{j k h}^i V^h = 0. \quad (2.7)$$

Thus, we state

Theorem (2.4). In a Finsler space F_n with non-symmetric connection admitting affine motion, the relation (2.7) holds if the vector V^i is parallel.

3. Special Form

Consider the existence of affine motion in following form

$$\ddot{x}^i = \dot{x}^i + v(x) dt, \quad V_{Ij}^i = \rho \delta_j^i, \quad (3.1)$$

Here $\rho(x, \dot{x})$ is an arbitrary non-scalar function and it is homogeneous of degree zero in its directional arguments $\dot{x}^i$.

Introducing the relation (3.1) and (2.3) in (1.10), we find

$$R_{hjk I s}^i + V^s + R_{sjk}^i (\rho \delta_h^s) + R_{hsk}^i (\rho \delta_j^s) + R_{hjs}^i (\rho \delta_k^s) - R_{hjk}^i (\rho \delta_s^i) + \partial_r R_{hjk}^i (\rho \delta_s^r) \dot{x}^s = 0$$

or

$$R_{hjk I s}^i + V^s + 2\rho R_{hjk}^i + \rho \partial_s R_{hjk}^i \dot{x}^s = 0. \quad (3.2)$$

Due to homogeneity property of R_{hjk}^i , we have

$$\partial_s R_{hjk}^i \dot{x}^s = 0. \quad (3.3)$$

Using (3.3) in (3.2), we get

$$2\rho R_{hjk}^i + R_{hjk I s}^i + V^s = 0. \quad (3.4)$$

Contracting the equation (3.4) for the indices i and k and transvecting by $\dot{x}^h$, $\dot{x}^j$ successively, we get

$$2\rho R_{hj} \dot{x}^h \dot{x}^j + R_{hj I s} + \dot{x}^h \dot{x}^j V^s = 0. \quad (3.5)$$

Using (1.13)(a) in (3.5), we get

$$2\rho R_{hj} \dot{x}^h \dot{x}^j + \left(R_{hj} \dot{x}^h \dot{x}^j \right)_{+I s} \dot{x}^h \dot{x}^j V^s = 0. \quad (3.6)$$

Assume a non-null scalar function $S(x, \dot{x})$ defined as

$$S(x, \dot{x}) \stackrel{\text{def}}{=} R_{hj} \dot{x}^h \dot{x}^j. \quad (3.7)$$

In view of relation (3.7), (3.6) reduces to

$$2\rho S + S_{+I s} V^s = 0. \quad (3.8)$$

Thus we conclude following :

Theorem (3.1). In a Finsler space F_n with non-symmetric connection admitting the affine motion of form (3.1), the non-null scalar function $S(x, \dot{x})$ defined by (3.7) satisfies the differential equation (3.8).

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