

On P2-Like Finsler Spaces

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(Received : 15 July, 2008)

Abstract

In the present paper we have discussed a special form of (v) hv-torsion tensor P_{ijk} given by $P_{ijk} = \lambda X_i X_j X_k$, where X_i are covariant components of unit vector, λ is a scalar function of x, y in a Finsler space. Since P_{ijk} of every two dimensional Finsler space may be written in this form, we shall say an n -dimensional Finsler space F^n ($n \geq 2$) as P2-like Finsler space whose P_{ijk} is of this form. The values of λ and X_i are obtained in terms of main scalars and h-connection vectors with respect to orthonormal frame in three and four dimensional P2-like Finsler spaces.

Keywords. P2-like three and four dimensional Finsler spaces.

Mathematics Subject Classification 2000 : 53B40, 53B18.

1. Introduction

There are three kinds of torsion tensors in Cartan's theory of Finsler spaces. Two of them are (h) hv-torsion tensor C_{ijk} and (v) hv-torsion tensor P_{ijk} which are symmetric in all their indices and both are indicatory tensors. Various interesting special forms of these torsion tensors have been studied by mathematicians. For example C-reducible [2], semi-C-reducible [3], [4], C2-like [4] and C3-like [7] Finsler spaces are based on the special forms of C_{ijk} where as P-reducible [1], [5] and P-symmetric [5] Finsler spaces are based on the special forms of P_{ijk} .

In the present paper we shall discuss another special form P_{ijk} given by

$$P_{ijk} = \lambda X_i X_j X_k, \quad (1.1)$$

where X_i are covariant components of unit vector λ is a scalar function of x and y .

It should be remarked here that a P2-like Finsler space is a Landsberg space if and only if $\lambda = 0$.

2. n-Dimensional P2-like Finsler space.

Let F^n be an n-dimensional Finsler space with the metric function $L(x, y)$. We denote $g_{ij}(x, y)$ as the fundamental metric tensor : $g_{ij} = \frac{1}{2} \dot{\partial}_i \dot{\partial}_j L^2$; $C_{ijk}(x, y)$, the (h) hv-torsion tensor : $C_{ijk} = \frac{1}{2} \dot{\partial}_k g_{ij}$. The h-covariant derivative of C_{ijk} with respect to Cartan's connection CT , is used in defining (v) hv-torsion tensor P_{ijk} :

$$P_{ijk} = C_{ijk| h} y^h = C_{ijk| 0}.$$

Let X_i are components of a covariant unit vector in F^n . Then we consider the special form of P_{ijk} given by

$$P_{ijk} = \lambda X_i X_j X_k, \quad (2.1)$$

where λ is a scalar function of x, y and we call F^n as P2-like Finsler space if its P_{ijk} is of this form. Since P_{ijk} is a symmetric tensor and $P_{ijk} y^j = 0$ from (2.1) it follows that $X_i y^i = 0$. The v-covariant derivative of this equation with respect to CT gives

$$X_i | _j y^j + X_j = 0. \quad (2.2)$$

If the vector field X_i is v-covariantly constant then from (2.2) it follows that $X_j = 0$, which is a contradiction. Hence we have the following :

Proposition (2.1). The vector field X_i occuring in P2-like Finsler space is not v-covariantly constant.

The concurrent vector field has been defined by Matsumoto [6] and Tachibana [12]. The semi-parallel vector field, the semi-parallel h-vector field and the concircular vector fields have been defined by Singh and Prasad [10], Singh and Kumari [11] and Prasad et al. [8] respectively. In all these works the vector field are v-covariantly constant. Hence, we may state that

Proposition (2.2). The vector field X_i occuring in P2-like Finsler space is none of the following :

- (a) a concurrent vector field (b) a semi-parallel vector field,
 (b) a semi-parallel h-vector field (d) a concircular vector field.

Contracting (2.1) with g^{jk} , using the fact that X_i are components of unit covariant vector and $C_{i|0} = P_i = P_{ijk} g^{jk}$, we get $\lambda X_i = C_{i|0}$. This shows that λ is the magnitude of the vector $C_{i|0}$, i.e.,

$$\lambda^2 = g^{ij} C_{i|0} C_{j|0}.$$

3. Two and three-dimensional P2-like Finsler space.

First of all we consider the two dimensional Finsler space in which the Berwald's frame (l_i, m_i) plays an important role. With respect to his frame, the metric tensor and (h) hv-torsion tensor are respectively given by [3]

$$g_{ij} = l_i l_j + m_i m_j \quad \text{and} \quad LC_{ijk} = I m_i m_j m_k,$$

where I is main scalar of two dimensional Finsler space F^2 . Since $m_i|_j = 0$ in F^2 , we have $LC_{ijk|_h} = I|_h m_i m_j m_k$, which gives $P_{ijk} = C_{ijk|0} = L^{-1} I|_0 m_i m_j m_k$. Thus we have the following :

Theorem (3.1). Every two dimensional Finsler space is P2-like with $\lambda = L^{-1} I|_0$ and $X_i = m_i$.

Now we consider the three-dimensional Finsler space F^3 in which the Moor's frame (l_i, m_j, n_i) plays the important role. With respect to his frame, the metric tensor and (h) hv-torsion tensor are respectively given by

$$g_{ij} = l_i l_j + m_i m_j + n_i n_j$$

and

$$LC_{ijk} = H m_i m_j m_k - J \pi_{(ijk)} \{m_i m_j n_k\} + I \pi_{(ijk)} \{m_i n_j n_k\} + J m_i n_j n_k \quad (3.1)$$

where H, I, J are main scalar of three-dimensional Finsler space F^3 such that $H + I = LC$ [3] and $\pi_{(ijk)} \{ \}$ stands for cyclic permutation of i, j, k and summation. Taking h-covariant derivative of (3.1), using [3]

$$m_i|_j = n_i h_j, \quad n_i|_j = -m_i h_j,$$

and then contracting the resulting equation with y^h , we get

$$P_{ijk} = (H_{,1} + 3J h_1) m_i m_j m_k + (J_{,1} + 3I h_1) n_i n_j n_k + \{-J_{,1} + (H - 2I) h_1\} \pi_{(ijk)} \{m_i m_j n_k\} + (I_{,1} - 3J h_1) \pi_{(ijk)} \{m_i n_j n_k\}, \quad (3.2)$$

where h_i are components of h connection vector and

$$h_1 = h_i l^i, H_{,1} = \left(\frac{\partial H}{\partial x^h} - \frac{\partial H}{\partial y^r} G_h^r \right) l^h \text{ etc.}$$

If X_α ($\alpha = 1, 2, 3$) are scalar components of X_i with respect to Moor's frame (l_i, m_i, n_i) , i.e.

$$X_i = X_1 l_i + X_2 m_i + X_3 n_i. \quad (3.3)$$

Then $X_i y^i = 0$ implies that $X_1 = 0$ and $g^{ij} X_i X_j = 1$ implies that

$$X_2^2 + X_3^2 = 1. \quad (3.4)$$

If F^3 is P2-like Finsler space, then from (2.1) and (3.3), we get

$$P_{ijk} = \lambda [X_2^3 m_i m_j m_k + X_3^3 n_i n_j n_k + X_2^2 X_3 \pi_{(ijk)} \{m_i m_j n_k\} + X_2 X_3^2 \pi_{(ijk)} \{m_i n_j n_k\}]. \quad (3.5)$$

Comparing (3.2) with (3.5), we get

$$\begin{aligned} \text{(a)} \quad \lambda X_2^3 &= H_{,1} + 3J h_1, & \text{(b)} \quad \lambda X_3^3 &= J_{,1} + 3I h_1, \\ \text{(c)} \quad \lambda X_2^2 X_3 &= -J_{,1} + (H - 2I) h_1, & \text{(d)} \quad \lambda X_2 X_3^2 &= I_{,1} - 3J h_1. \end{aligned} \quad (3.6)$$

Adding (a) and (d) of equation (3.6), using (3.4) and the fact that $H + I = LC$, we get $(LC)_{,1} = \lambda X_2$. Similarly adding (b) and (c) of equation (3.6), using (3.4) and the fact that $H + I = LC$, we get $LCh_1 = \lambda X_3$. Therefore

$$\lambda X_i = (LC)_{,1} m_i + LC h_1 n_i, \quad (3.7)$$

and

$$\lambda^2 = [(LC)_{,1}]^2 + L^2 C^2 h_1^2. \quad (3.8)$$

Theorem (3.2). In a three dimensional P2-like Finsler space the unit vector field X_i and the scalar λ are given by (3.7) and (3.8).

Now we consider the particular case of P2-like three dimensional Finsler space for which $X_i = m_i$. Then we have $X_2 = 1, X_3 = 0$. Therefore (3.6) reduces to

$$\begin{aligned} (a) \quad H_{,1} + 3J h_1 &= \lambda, & (b) \quad J_{,1} + 3I h_1 &= 0, \\ (c) \quad -J_{,1} + (H - 2I) h_1 &= 0, & (d) \quad I_{,1} - 3J h_1 &= 0. \end{aligned} \quad (3.9)$$

Solving these equations, we get

$$h_1 = 0, \quad H_{,1} = \lambda, \quad J_{,1} = I_{,1} = 0,$$

provided unified main scalar LC is non-zero.

Theorem (3.3). If the vector field X_i in three dimensional P2-like Finsler space is along one of the vector m_i of the Moor's frame (l_i, m_i, n_i) then $h_1 = 0, H_{,1} = \lambda, J_{,1} = I_{,1} = 0$, provided unified main scalar LC is non-zero.

Next suppose that $X_i = n_i$. Then $X_2 = 0, X_3 = 1$ and hence (3.6) reduces to

$$\begin{aligned} (a) \quad H_{,1} + 3J h_1 &= 0, & (b) \quad J_{,1} + 3I h_1 &= \lambda, \\ (c) \quad -J_{,1} + (H - 2I) h_1 &= 0, & (d) \quad I_{,1} - 3J h_1 &= 0. \end{aligned}$$

Solving these equations and using the fact that $H + I = LC$ we get $(LC)_{,1} = 0, LCh_1 = \lambda$.

Theorem (3.4). If the vector field X_i in three dimensional P2-like Finsler space is along one of the vector n_i of the Moor's frame (l_i, m_i, n_i) then $(LC)_{,1} = 0$ and $\lambda = LCh_1$.

4. Four dimensional P2-like Finsler space

We consider the four-dimensional Finsler space F^4 in which the Moor's frame (l_i, m_i, n_i, p_i) plays the important role. With respect to his frame, the metric tensor and (h) hv-torsion tensor are respectively given by

$$g_{ij} = l_i l_j + m_i m_j + n_i n_j + p_i p_j$$

and

$$\begin{aligned} LC_{ijk} &= Hm_i m_j m_k + J \{n_i n_j n_k\} + H' p_i p_j p_k + I \pi_{(ijk)} \{m_i n_j n_k\} \\ &\quad + K \pi_{(ijk)} \{m_i p_j p_k\} - (J + J') \pi_{(ijk)} \{m_i m_j n_k\} + J' \pi_{(ijk)} \{n_i p_j p_k\} \end{aligned}$$

$$\begin{aligned}
& - (H' + I') \pi_{(ijk)} \{m_i m_j p_k\} + I' \pi_{(ijk)} \{n_i n_j p_k\} \\
& + K' \pi_{(ijk)} \{m_i (n_j p_k + n_k p_j)\}, \quad (4.1)
\end{aligned}$$

where H, I, J, K, H', I', J' and K' are eight main scalars of F^4 . Taking h-covariant derivative of (4.1), using [9]

$$m_i |_{j_1} = n_i h_{j_1} + p_i j_{j_1}; \quad n_i |_{j_1} = -m_i h_{j_1} + p_i k_{j_1}; \quad p_i |_{j_1} = -m_i j_{j_1} - n_i k_{j_1}, \quad (4.2)$$

and then contracting the resulting equation with y^h , we get

$$\begin{aligned}
P_{ijk} = & [H_{,1} + 3(J + J') h_1 + 3(H' + I') J_1] m_i m_j m_k + [J_{,1} + 3I h_1 - 3I' k_1] n_i n_j n_k \\
& + [H'_{,1} + 3K j_1 + 3J' k_1] p_i p_j p_k + [-(J + J')_{,1} + (H - 2I) h_1 - 2K' j_1 + \\
& (H' + I') k_1] \pi_{(ijk)} \{m_i m_j n_k\} + [I_{,1} - (3J + 2J') h_1 - I' J_1 - 2K' k_1] \\
& \pi_{(ijk)} \{m_i n_j n_k\} + [K_{,1} - J' h_1 - (3H' + 2I') J_1 + 2K' k_1] \pi_{(ijk)} \{m_i p_j p_k\} \\
& + [J'_{,1} + K h_1 + 2K' j_1 - (H' - 2I') k_1] \pi_{(ijk)} \{n_i p_j p_k\} + [I'_{,1} + 2K' h_1 + I j_1 \\
& + (J - 2J') k_1] \pi_{(ijk)} \{n_i n_j p_k\} + [-(H' + I')_{,1} - 2K' h_1 + (H - 2K) j_1 \\
& - (J + J') k_1] \pi_{(ijk)} \{m_i m_j p_k\} + [K'_{,1} + (H' + 2I') h_1 - (J' + 2J') j_1 \\
& + (I - K) k_1] \pi_{(ijk)} \{m_i n_j p_k + m_i p_j n_k\} \quad (4.3)
\end{aligned}$$

where h_i, j_i, k_i are components of three h connection vectors in F^4 and

$$h_1 = h_i l^i, \quad j_1 = j_i l^i, \quad k_1 = k_i l^i, \quad H_{,1} = \left(\frac{\partial H}{\partial x^h} - \frac{\partial H}{\partial y^r} G_t^{r\ h} \right) l^h \text{ etc.}$$

Let X_α ($\alpha = 1, 2, 3, 4$) are scalar components of X_i with respect to Moor frame (l_i, m_i, n_i, p_i) , i.e.,

$$X_i = X_1 l_i + X_2 m_i + X_3 n_i + X_4 p_i. \quad (4.4)$$

Then $X_i y^i = 0$ implies that $X_1 = 0$ and $g^{ij} X_i X_j = 1$ implies that

$$X_2^2 + X_3^2 + X_4^2 = 1. \quad (4.5)$$

If F^4 is P2-like Finsler space, then from (2.3) and (4.5), we get

$$\begin{aligned}
P_{ijk} = & \lambda [X_2^3 m_i m_j m_k - X_3^3 n_i n_j n_k + X_4^3 p_i p_j p_k + X_2^2 X_3 \pi_{(ij k)} \{m_i m_j n_k\} \\
& + X_2 X_3^2 \pi_{(ij k)} \{m_i n_j n_k\} + X_2 X_4^2 \pi_{(ij k)} \{m_i p_j p_k\} \\
& + X_3 X_4^2 \pi_{(ij k)} \{n_i p_j p_k\} + X_4 X_3^2 \pi_{(ij k)} \{p_i n_j n_k\} + X_4 X_2^2 \pi_{(ij k)} \{p_i m_j m_k\} \\
& + X_2 X_3 X_4 \pi_{(ij k)} \{m_i n_j p_k + m_i p_j n_k\}] . \tag{4.6}
\end{aligned}$$

Comparing (4.3) and (4.6), we get

$$\begin{aligned}
(a) \quad & \lambda X_2^3 = H_{,1} + 3(J + J') h_1 + 3(H' + I') J_1, \\
(b) \quad & \lambda X_3^3 = J_{,1} + 3I h_1 - 3I' k_1, \\
(c) \quad & \lambda X_4^3 = H'_{,1} + 3K j_1 + 3J' k_1, \\
(d) \quad & \lambda X_2^2 X_3 = -(J + J')_{,1} + (H - 2I) h_1 - 2K' j_1 + (H' + I') k_1, \\
(e) \quad & \lambda X_2 X_3^2 = I_{,1} - (3J + 2J') h_1 - I' j_1 - 2K' k_1, \tag{4.7} \\
(f) \quad & \lambda X_2 X_4^2 = K_{,1} - J' h_1 - (3H' + 2I') j_1 + 2K' k_1, \\
(g) \quad & \lambda X_3 X_4^2 = J'_{,1} + K h_1 + 2K' j_1 - (H' - 2I') k_1, \\
(h) \quad & \lambda X_3 X_3^2 = I'_{,1} + 2K' h_1 + I j_1 + (J - 2J') k_1, \\
(i) \quad & \lambda X_4 X_2^2 = -(H' + I')_{,1} - 2K' h_1 + (H - 2K) j_1 + (J + J') k_1, \\
(j) \quad & \lambda X_2 X_3 X_4 = K'_{,1} - (H' + 2I') h_1 - (J + 2J') j_1 + (I - K) k_1.
\end{aligned}$$

Adding (a), (e) and (f) of equation (4.7), using (4.5) and the fact that $H + I + K = LC$, we get $(LC)_{,1} = \lambda X_2$. Also adding (b), (d) and (g) of equation (4.7), using (4.5) and the fact that $H + I + K = LC$, we get $LC h_1 = \lambda X_3$. Similarly adding (c), (h) and (i) of equation (4.7), using (4.5) and the fact that $H + I + K = LC$, we get $LC j_1 = \lambda X_4$. Therefore

$$\lambda X_i = (LC)_{,1} m_i + LC (h_1 n_i + j_1 p^i) \quad (4.8)$$

and

$$\lambda^2 = [(LC)_{,1}]^2 + L^2 C^2 (h_1^2 + j_1^2). \quad (4.9)$$

Theorem (4.1). In a four dimensional P2-like Finsler space the unit vector field X_i and the scalar λ are given by (4.8) and (4.9).

Now we consider the particular case of P2-like four dimensional space for which $X_i = m_i$. Then we have $X_2 = 1$, $X_3 = X_4 = 0$. Therefore (4.7) reduces to

$$\begin{aligned} (a) \quad & H_{,1} + 3(J + J') h_1 + 3(H' + I') J_1 = \lambda, \\ (b) \quad & J_{,1} + 3I h_1 - 3I' k_1 = 0, \\ (c) \quad & H'_{,1} + 3K j_1 + 3J' k_1 = 0, \\ (d) \quad & -(J + J')_{,1} + (H - 2I) h_1 - 2K' j_1 + (H' + I') k_1 = 0, \\ (e) \quad & I_{,1} - (3J + 2J') h_1 - I' j_1 - 2K' k_1 = 0, \\ (f) \quad & K_{,1} - J' h_1 - (3H' + 2I') j_1 + 2K' k_1 = 0, \\ (g) \quad & J'_{,1} + K h_1 + 2K' j_1 - (H' - 2I') k_1 = 0, \\ (h) \quad & I'_{,1} + 2K' h_1 + I j_1 + (J - 2J') k_1 = 0, \\ (i) \quad & -(H' + I')_{,1} - 2K' h_1 + (H - 2K) j_1 + (J + J') k_1 = 0, \\ (j) \quad & K'_{,1} - (H' + 2I') h_1 - (J + 2J') j_1 + (I - K) k_1 = 0. \end{aligned} \quad (4.10)$$

Solving these equations we get $h_1 = 0$, $j_1 = 0$, $H_{,1} = 1$ and

$$\frac{J_{,1}}{2I'} = \frac{H'_{,1}}{-3J'} = \frac{I_{,1}}{2K'} = \frac{K_{,1}}{-2K'} = \frac{J'_{,1}}{H' - 2I'} = \frac{I'_{,1}}{-(J - 2J')} = \frac{K'_{,1}}{-(I - K)} = k_1, \quad (4.11)$$

provided unified main scalar LC is non-zero.

Theorem (4.2). If the vector field X_i in four dimensional P2-like Finsler space is along one of the vector m_i of Moor's frame (l_i, m_i, n_i, p_i) then $h_1 = 0$, $j_1 = 0$, $H_{,1} = \lambda$, provided unified main scalar LC is non-zero and (4.11) holds.

Next suppose that $X_i = n_i$. Then $X_2 = X_4 = 0$, $X_3 = 1$ and hence (4.5) reduces to the same equations as given in (4.8) except the equations (a) and (b) which now become

$$(a) \quad H_{,1} + 3(J + J') h_1 + 3(H' + I') J_1 = 0, \quad (b) \quad J_{,1} + 3I h_1 - 3I' k_1 = \lambda, \quad (4.12)$$

Solving these equations and using the fact that $H + I + K = LC$ we get $(LC)_{,1} = 0$,

$$LCh_1 = \lambda, \quad h_1 = \frac{H_{,1}}{-3(J + J')}, \quad j_1 = 0, \quad k_1 = \frac{H'_{,1}}{3J'}. \quad \text{Hence we have the following :}$$

Theorem (4.3). If the vector field X_i in four dimensional P2-like Finsler space is along one of the vector n_i Moor's frame (l_i, m_i, n_i, p_i) then $(LC)_{,1} = 0$, $\lambda = LCh_1$,

$$h_1 = \frac{H_{,1}}{-3(J + J')}, \quad j_1 = 0 \quad \text{and} \quad k_1 = \frac{H'_{,1}}{3J'}.$$

Lastly suppose that $X_i = p_i$. Then $X_2 = X_3 = 0$, $X_4 = 1$ and hence (4.7) reduces to the same equations as given in (4.10) except the equations (a) and (c) which now becomes

$$(a) \quad H_{,1} + 3(J + J') h_1 + 3(H' + I') J_1 = 0, \quad (b) \quad H'_{,1} + 3Kj_1 + 3J' k_1 = \lambda. \quad (4.13)$$

Solving these equations and using the fact that $H + I + K = LC$, we get $(LC)_{,1} = 0$, $h_1 = 0$, $LCj_1 = \lambda$, $j_1 = \frac{H_{,1}}{-3(H' + I')}$ and $k_1 = \frac{J'_{,1}}{3I'}$. Hence, we have the following :

Theorem (4.4). If the vector field X_i in four dimensional P2-like Finsler space is along one of the vector p_i Moor's frame (l_i, m_i, n_i, p_i) then $(LC)_{,1} = 0$, $h_1 = 0$, $LCj_1 = \lambda$, $j_1 = \frac{H_{,1}}{-3(H' + I')}$ and $k_1 = \frac{J'_{,1}}{3I'}$.

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