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On Extended Generalized Concircular ϕ –Recurrent Lorentzian α –Sasakian Manifold

S. Shashikala and Venkatesha

Department of Mathematics, Kuvempu University
Shankaraghatta – 577451, Shimoga, Karnataka, India
e-mail: shashikalasampath@yahoo.com, vensmath@gmail.com
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Abstract

In this paper we have studied the extended generalized concircularly ϕ –recurrent Lorentzian α –Sasakian manifold and obtained some important results.

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1. Introduction

A transformation of an n –dimensional Riemannian manifold M , which transform every geodesic circle of M into a geodesic circle, is called a concircular transformation [8], [16]. A concircular transformation is always a conformal transformation. Here geodesic circle means a curve in M whose first curvature is constant and second curvature is identically zero. Thus, the geometry of concircular transformations, that is, the concircular geometry, is a generalization of inversive geometry in the sense that the change of metric is more general than that induced by a circle preserving diffeomorphism. An interesting invariant of a concircular transformation is the concircular curvature tensor.

The notion of local symmetry of a Riemannian manifold has been studied by many authors in several ways to a different extent. As a weaker version of local symmetry in 1977, Takahashi [15] introduced the notion of locally ϕ –symmetric Sasakian manifold and obtained several interesting results. In 1979 Dubey [3] introduced the notion of generalized recurrent manifold and in 2007, Özgür [9], studied generalized recurrent Kenmotsu manifold. Generalizing this notion, Basari and Murathan [2], introduced the notion of generalized ϕ –recurrency to Kenmotsu manifolds. Later in 2009, De, Yildiz and Yaliniz

[7], studied ϕ -recurrent Kenmotsu manifolds, generalized ϕ -recurrent Sasakian manifold and Lorentzian α -Sasakian manifolds are studied in [10, 11]. Extending the notion of generalized ϕ -recurrency, Shaikh and Hui [14], introduced the notion of extended generalized ϕ -recurrency to β -Kenmotsu manifolds. The manifold M^n ($n > 2$), is called generalized recurrent [3], if its curvature tensor R of type $(1, 3)$ satisfies the condition

$$\nabla R = A \otimes R + B \otimes G, \quad (1.1)$$

where A and B are nowhere vanishing unique 1-forms defined by $A(\cdot) = g(\cdot, \rho_1)$, $B(\cdot) = g(\cdot, \rho_2)$ and G is a tensor of type $(1, 3)$ given by

$$G(X, Y)Z = g(Y, Z)X - g(X, Z)Y, \quad (1.2)$$

for all vector fields $X, Y, Z \in \chi(M)$; $\chi(M)$ being the Lie algebra of all smooth vector fields on M and ∇ is the Levi-Civita connection.

Again M^n ($n > 2$) is called generalized Ricci-recurrent manifold [5] if its Ricci tensor S of type $(0, 2)$ satisfies the condition

$$\nabla S = A \otimes S + B \otimes g, \quad (1.3)$$

where A and B are nowhere vanishing unique 1-forms.

This paper is organized as follows: Section 2 deals with a brief account of Lorentzian α -Sasakian manifolds. In Section 3, we obtain the necessary and sufficient condition for a concircular manifold to be a generalized ϕ -recurrent. Also it is shown that in a generalized concircularly ϕ -recurrent Lorentzian α -Sasakian manifold the vector field ρ_2 associated with the 1-form B and the characteristic vector field ξ are co-directional. Further, it is shown that the extended generalized concircularly ϕ -recurrent Lorentzian α -Sasakian manifold is a super generalized Ricci-recurrent manifold.

2. Preliminaries

A differentiable manifold M^n of dimension n is called a Lorentzian α -Sasakian manifold if it admits a $(1, 1)$ -tensor field ϕ , a contravariant vector field ξ , a covariant vector field η and a Lorentzian metric g which satisfy: [11],

$$(a) \quad \eta(\xi) = -1, \quad (b) \quad \phi(\xi) = 0, \quad (c) \quad \eta(\phi X) = 0, \quad (2.1)$$

$$(a) \quad \phi^2 X = X + \eta(X)\xi, \quad (b) \quad g(X, \xi) = \eta(X), \quad (2.2)$$

$$g(\phi X, \phi Y) = g(X, Y) + \eta(X)\eta(Y), \quad (2.3)$$

$$(\nabla_X \phi)Y = \alpha(g(X, Y)\xi + \eta(Y)X), \quad (2.4)$$

for all $X, Y \in TM$.

Also a Lorentzian α -Sasakian manifold M^n satisfies,

$$\nabla_X \xi = \alpha \phi X, \quad (2.5)$$

$$(\nabla_X \eta)(Y) = \alpha g(X, \phi Y), \quad (2.6)$$

where ∇ denotes the operator of covariant differentiation with respect to the Lorentzian metric g . Further, on a Lorentzian α -Sasakian manifold M^n , the following relations hold:[18],

$$\eta(R(X, Y)Z) = \alpha^2[g(Y, Z)\eta(X) - g(X, Z)\eta(Y)], \quad (2.7)$$

$$R(X, Y)\xi = \alpha^2[\eta(Y)X - \eta(X)Y], \quad (2.8)$$

$$S(X, \xi) = (n-1)\alpha^2\eta(X), \quad (2.9)$$

$$Q\xi = (n-1)\alpha^2\xi, \quad (2.10)$$

$$S(\phi X, \phi Y) = S(X, Y) + (n-1)\alpha^2\eta(X)\eta(Y), \quad (2.11)$$

$$(\nabla_W S)(Y, \xi) = \alpha((n-1)\alpha^2g(W, \phi Y) - S(\phi W, Y)), \quad (2.12)$$

$$(\nabla_W R)(X, Y)\xi = \alpha[\alpha^2(g(\phi Y, W)X - g(\phi X, W)Y) - R(X, Y, \phi W)], \quad (2.13)$$

where S is the Ricci curvature and Q is the Ricci operator given by $S(X, Y) = g(QX, Y)$.

Definition 2.1. A Lorentzian α -Sasakian manifold is said to be locally ϕ -symmetric if

$$\phi^2((\nabla_W R)(X, Y)Z) = 0, \quad (2.14)$$

for all vector fields X, Y, Z, W orthogonal to ξ .

Definition 2.2. A Lorentzian α -Sasakian manifold is said to be generalized ϕ -recurrent if its curvature tensor R satisfies the condition ([4])

$$\phi^2((\nabla_W R)(X, Y)Z) = A(W)R(X, Y)Z + B(W)[g(Y, Z)X - g(X, Z)Y] \quad (2.15)$$

where A and B are two 1-forms and B is non-zero.

Definition 2.3. A Lorentzian α -Sasakian manifold is said to be concircularly ϕ -recurrent if there exists a nowhere vanishing unique 1-form A such that

$$\phi^2((\nabla_W \bar{C})(X, Y)Z) = A(W)\bar{C}(X, Y)Z, \quad (2.16)$$

for all vector fields $X, Y, Z, W \in \chi(M)$.

3. Extended Generalized Concircular ϕ -recurrent Lorentzian α -Sasakian Manifolds

A Lorentzian α -Sasakian manifold $M^n(\phi, \xi, \eta, g)$, is said to be an extended generalized concircular ϕ -recurrent if its concircular curvature tensor \overline{C} satisfies the relation

$$\begin{aligned} \phi^2((\nabla_W \overline{C})(X, Y)Z) &= A(W)\phi^2(\overline{C}(X, Y)Z) \\ &\quad + B(W)\phi^2(G(X, Y)Z), \end{aligned} \quad (3.1)$$

where A and B are non-vanishing 1-forms, ∇ denotes the operator of covariant differentiation with respect to the metric g i.e., ∇ is the Riemannian connection, and the Concircular curvature tensor \overline{C} of type $(1, 3)$ is given by

$$\overline{C}(X, Y)Z = R(X, Y)Z - \frac{r}{n(n-1)}G(X, Y)Z, \quad (3.2)$$

where r is the scalar curvature of the manifold.

Let us consider an extended generalized concircularly ϕ -recurrent Lorentzian α -Sasakian manifold $M^n(\phi, \xi, \eta, g)$. Then by virtue of (2.2), it follows from (3.1) that

$$\begin{aligned} \phi^2((\nabla_W R)(X, Y)Z) &- A(W)\phi^2(R(X, Y)Z) - B(W)\phi^2(G(X, Y)Z) \\ &= \frac{dr(W) - rA(W)}{n(n-1)}[g(Y, Z)X - \eta(X)g(Y, Z)\xi \\ &\quad - g(X, Z)Y + \eta(Y)g(X, Z)\xi]. \end{aligned} \quad (3.3)$$

This leads to the following:

Theorem 3.1. An extended generalized concircularly ϕ -recurrent Lorentzian α -Sasakian manifold $M, n \geq 3$ is generalized ϕ -recurrent if and only if

$$\begin{aligned} \frac{dr(W) - rA(W)}{n(n-1)}[g(Y, Z)X + \eta(X)g(Y, Z)\xi - g(X, Z)Y \\ - \eta(Y)g(X, Z)\xi] = 0. \end{aligned} \quad (3.4)$$

Now taking inner product of (3.4) with U , we have

$$\begin{aligned} \frac{dr(W) - rA(W)}{n(n-1)}[g(Y, Z)g(X, U) + \eta(X)g(Y, Z)\eta(U) - g(X, Z)g(Y, U) \\ - \eta(Y)g(X, Z)\eta(U)] = 0. \end{aligned}$$

contracting over X and U , we get

$$\{dr(W) - rA(W)\}[ng(Y, Z) - \eta(Y)\eta(Z)] = 0. \quad (3.5)$$

Again contracting (3.5) over Y and Z , we get

$$\{dr(W) - rA(W)\}[n^2 - 1] = 0. \quad (3.6)$$

which implies that

$$\begin{aligned} A(W) &= \frac{1}{r}dr(W) \text{ for all } W \text{ and } r \neq 0 \\ \text{i.e., } \rho_1 &= \frac{1}{r} \text{grad } r, \text{ where } A(W) = g(W, \rho_1). \end{aligned} \quad (3.7)$$

This leads to the following:

Theorem 3.2. If an extended generalized concircularly ϕ -recurrent Lorentzian α -Sasakian manifold M , $n \geq 3$ is generalized ϕ -recurrent, then the associated vector field corresponding to the 1-form A is given by $\rho_1 = \frac{1}{r} \text{grad } r$, r being non-zero and non-constant scalar curvature of the manifold.

Now by virtue of (2.2), it follows from (3.3) that

$$\begin{aligned} (\nabla_W R)(X, Y)Z &= -\eta((\nabla_W R)(X, Y)Z)\xi + A(W)[R(X, Y)Z + \eta(R(X, Y)Z)\xi] \\ &\quad + B(W)[G(X, Y)Z + \eta(G(X, Y)Z)\xi] + \frac{dr(W) - rA(W)}{n(n-1)} \\ &\quad [g(Y, Z)X + \eta(X)g(Y, Z)\xi - g(X, Z)Y - \eta(Y)g(X, Z)\xi]. \end{aligned} \quad (3.8)$$

Taking inner product of (3.8) with U and then contracting over X and U , and using (2.4), (2.7) and (2.12), we get

$$\begin{aligned} (\nabla_W S)(Y, Z) &= A(W)S(Y, Z) + [nB(W) + \alpha^2 A(W)]g(Y, Z) \\ &\quad + \frac{dr(W)}{n(n-1)}[ng(Y, Z) - \eta(Y)\eta(Z)] + A(W)\left[\left(-\alpha^2 + \frac{r}{n(n-1)}\right)\right. \\ &\quad \left.\eta(Y)\eta(Z) - \frac{rn}{n(n-1)}g(Y, Z)\right] - B(W)\eta(Y)\eta(Z). \end{aligned} \quad (3.9)$$

Again taking contraction over Y and Z in (3.9), we get

$$dr(W) = [r - \alpha^2 n(n-1)]A(W) - n(n^2 - 1)B(W). \quad (3.10)$$

From (3.10), we can state the following:

Theorem 3.3. In an extended generalized concircularly ϕ -recurrent Lorentzian α -Sasakian manifold M , $n \geq 3$, the associated 1-forms A and B are related by the relation (3.10)

Corollary 3.1. In an extended generalized concircularly ϕ -recurrent Lorentzian α -Sasakian manifold M , $n \geq 3$, with constant scalar curvature, the associated 1-forms A and B are related by

$$\{r - \alpha^2 n(n-1)\}A - n(n^2 - 1)B = 0$$

Now using (3.10) in (3.9), we get

$$\begin{aligned} (\nabla_W S)(Y, Z) = & A(W)S(Y, Z) + \{(-n^2)B(W) + \alpha^2(1-n)A(W)\}g(Y, Z) \\ & + nB(W)\eta(Y)\eta(Z). \end{aligned} \quad (3.11)$$

From (3.11), it follows that the Ricci tensor S satisfies the condition

$$\nabla S = \alpha \otimes S + \beta \otimes g + \gamma \otimes \pi, \quad (3.12)$$

where $\alpha(W) = A(W)$,

$$\begin{aligned} \beta(W) = & -n^2 B(W) + \alpha^2(1-n)A(W), \quad \gamma(W) = nB(W) \\ \text{and} \quad \pi = & \eta \otimes \eta. \end{aligned}$$

From (3.12), we can state the following:

Theorem 3.4. An extended generalized concircular ϕ -recurrent Lorentzian α -Sasakian manifold M , $n \geq 3$, is super generalized Ricci-recurrent manifold.

Now contracting (3.11) over W and Z , we get

$$\frac{1}{2}dr(Y) = S(Y, \rho_1) - n^2 B(Y) + \alpha^2(1-n)A(Y) + n\eta(Y)B(\xi). \quad (3.13)$$

By virtue of (3.10), the above relation takes the form

$$\begin{aligned} S(Y, \rho_1) = & \left[\frac{r - \alpha^2 n^2 + 3\alpha^2 n - 2\alpha^2}{2} \right] A(Y) \\ & - \left[\frac{n^3 - n + 2n^2}{2} \right] B(Y) - n\eta(Y)B(\xi). \end{aligned} \quad (3.14)$$

From (3.14), we can state the following:

Theorem 3.5. In an extended generalized concircularly ϕ -recurrent Lorentzian α -Sasakian manifold M , $n \geq 3$, the Ricci tensor in the direction of ρ_1 is given by (3.14).

Now setting $Z = \xi$ in (3.11) and then using (2.9), we get

$$\alpha S(\phi W, Y) = \alpha^3(n-1)g(W, \phi Y) + n(n+1)B(W)\eta(Y). \quad (3.15)$$

Replacing Y by ϕY in (3.15) and using (2.11) and (2.9), we have

$$\alpha S(W, Y) = \alpha^3(n-1)g(W, Y) \quad (3.16)$$

Replacing W by ϕW in (3.15) and then using (2.2), we get

$$\alpha S(W, Y) = \alpha^3(n-1)g(W, Y) + n(n+1)B(\phi W)\eta(Y). \quad (3.17)$$

From (3.16) and (3.17) we have

$$B(\phi W) = 0,$$

which implies that

$$B(W) = \eta(W)B(\xi).$$

This leads to the following:

Theorem 3.6. In an extended generalized concircularly ϕ -recurrent Lorentzian α -Sasakian manifold M , $n \geq 3$, the vector field ρ_2 associated with the 1-form B and the characteristic vector field ξ are codirectional.

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