

J. T. S.

Special Vol. 8 (2014), pp.113-120

<https://doi.org/10.56424/jts.v8i01.10553>

## $\eta$ -Ricci Solitons in $\alpha$ -Sasakian Manifolds

S. R. Ashoka, C. S. Bagewadi and Gurupadavva Ingalahalli

Department of Mathematics, Kuvempu University,  
Shankaraghatta - 577 451, Shimoga, Karnataka, INDIA  
e-mail: srashoka@gmail.com; prof\_bagewadi@yahoo.co.in;  
gurupadavva@gmail.com

(Received: November 11, 2013)

### Abstract

In this paper we study  $\eta$ -Ricci solitons in  $\alpha$ -Sasakian manifolds its shows that a symmetric second order covariant tensors in  $\alpha$ -Sasakian manifolds is a constant multiple of metric tensor using this it is shown that  $L_V g + 2S + 2\mu\eta \otimes \eta$  is parallel, where  $V$  is a given vector field then  $(g, V, \mu)$  is  $\eta$ -Ricci solitons.

**Key Words:** Ricci soliton,  $\alpha$ -Sasakian manifold, Einstein.

**2010 AMS Subject Classification:** 53C15, 53C20, 53C21, 53C25, 53D10.

### 1. Introduction

A Ricci soliton  $(g, V, \lambda)$  is a generalization of an Einstein metric and is defined on a Riemannian manifold  $(M, g)$  by

$$(1.1) \quad (\mathcal{L}_V g)(X, Y) + 2S(X, Y) + 2\lambda g(X, Y) = 0,$$

where  $V$  is a complete vector field on  $M$ , and  $\lambda$  is a constant. The Ricci soliton is said to be shrinking, steady or expanding according as  $\lambda$  is negative, zero and positive respectively.

A  $\eta$ -Ricci soliton [3, 9] is defined on a Riemannian manifold  $(M, g)$  by

$$(1.2) \quad (\mathcal{L}_V g)(X, Y) + 2S(X, Y) + 2\lambda g(X, Y) + 2\mu\eta(X)\eta(Y) = 0.$$

In [19], Perelman proved that a Ricci soliton on a compact  $n$ -manifold is a gradient Ricci soliton. In [23], R. Sharma studied Ricci solitons in K-contact manifolds, where the structure field  $\xi$  is Killing and he proved that a complete K-contact gradient soliton is compact Einstein and Sasakian. In [24], M. M. Tripathi studied Ricci solitons in  $N(k)$ -contact metric and  $(k, \mu)$  manifolds. In [1], Amadendu Ghosh and Ramesh Sharma studied K-contact metrics as Ricci solitons. In [18], H. G. Nagaraja and C. R. Premalatha studied Ricci

Solitons in  $f$ -Kenmotsu Manifolds and 3-dimensional trans-Sasakian manifolds. Recently, C. S. Bagewadi and Gurupadavva Ingalahalli [4] studied Ricci solitons in Lorentzian  $\alpha$ -Sasakian Manifolds. Motivated by the above studies on Ricci solitons, in this paper, we study  $\eta$ -Ricci solitons in an  $\alpha$ -Sasakian manifolds, where  $\alpha$  is some constant.

## 2. Preliminaries

Let  $M$  be an almost contact metric manifold of dimension  $n$  equipped with an almost contact metric structure  $(\phi, \xi, \eta, g)$  consisting of a  $(1, 1)$  tensor field  $\phi$ , a vector field  $\xi$ , a 1-form  $\eta$  and a Riemannian metric  $g$ , which satisfy

$$(2.1) \quad \phi^2 = -I + \eta \otimes \xi, \quad \eta(\xi) = 1, \quad \eta \circ \phi = 0, \quad \phi\xi = 0,$$

$$(2.2) \quad g(\phi X, \phi Y) = g(X, Y) - \eta(X)\eta(Y), \quad \eta(X) = g(X, \xi),$$

for all  $X, Y \in \mathfrak{X}(M)$ . An almost contact metric manifold  $M(\phi, \xi, \eta, g)$  is said to be  $\alpha$ -Sasakian manifold if the following conditions hold:

$$(2.3) \quad (\nabla_X \phi)Y = \alpha(g(X, Y)\xi - \eta(Y)X),$$

$$(2.4) \quad \nabla_X \xi = -\alpha\phi X, \quad (\nabla_X \eta)Y = \alpha g(X, \phi Y),$$

holds for some non zero constant  $\alpha$  on  $M$ .

In an  $\alpha$ -Sasakian manifold, the following relations hold:

$$(2.5) \quad R(X, Y)\xi = \alpha^2[\eta(Y)X - \eta(X)Y],$$

$$(2.6) \quad R(\xi, X)Y = \alpha^2[g(X, Y)\xi - \eta(Y)X],$$

$$(2.7) \quad \eta(R(X, Y)Z) = \alpha^2[g(Y, Z)\eta(X) - g(X, Z)\eta(Y)],$$

$$(2.8) \quad S(X, \xi) = \alpha^2(n-1)\eta(X),$$

$$(2.9) \quad S(\xi, \xi) = \alpha^2(n-1),$$

$$(2.10) \quad Q\xi = \alpha^2(n-1)\xi,$$

for all  $X, Y, Z \in \mathfrak{X}(M)$ , where  $R$  is the Riemannian curvature tensor,  $S$  is the Ricci tensor and  $Q$  is the Ricci operator.

**2.1. Example.** Let  $M = \{(x, y, z) \in R^3\}$ . Let  $(E_1, E_2, E_3)$  be linearly independent vector fields given by

$$(2.11) \quad E_1 = e^x \frac{\partial}{\partial y}, \quad E_2 = e^x \left[ \frac{\partial}{\partial x} + 2y \frac{\partial}{\partial z} \right], \quad E_3 = \frac{\partial}{\partial z}.$$

Let  $g$  be the Riemannian metric defined by  $g(E_1, E_2) = g(E_2, E_3) = g(E_1, E_3) = 0$ ,  $g(E_1, E_1) = g(E_2, E_2) = g(E_3, E_3) = 1$ , where  $g$  is given by

$$g = \frac{1}{e^{2x}}[(1 - 4e^{2x}y^2)dx \otimes dx + dy \otimes dy + e^{2x}dz \otimes dz].$$

Let  $\eta$  be the 1-form defined by  $\eta(U) = g(U, E_3)$  for any  $U \in \mathfrak{X}(M)$ . Let  $\phi$  be the  $(1, 1)$  tensor field defined by  $\phi E_1 = E_2$ ,  $\phi E_2 = -E_1$ ,  $\phi E_3 = 0$ . Then using the linearity of  $\phi$  and  $g$  yields that  $\eta(E_3) = 1$ ,  $\phi^2 U = -U + \eta(U)E_3$  and  $g(\phi U, \phi W) = g(U, W) - \eta(U)\eta(W)$  for any vector fields  $U, W \in \mathfrak{X}(M)$ . Thus for  $E_3 = \xi$ ,  $(\phi, \xi, \eta, g)$  defines a Sasakian structure on  $M$ . By definition of Lie bracket, we have

$$[E_1, E_2] = -e^x E_1 + 2e^{2x} E_3, \quad [E_1, E_3] = [E_2, E_3] = 0.$$

Let  $\nabla$  be the Levi-Civita connection with respect to above metric  $g$  Koszula formula is given by

$$\begin{aligned} 2g(\nabla_X Y, Z) &= X(g(Y, Z)) + Y(g(Z, X)) - Z(g(X, Y)) \\ (2.12) \quad &- g(X, [Y, Z]) - g(Y, [X, Z]) + g(Z, [X, Y]). \end{aligned}$$

Then

$$\begin{aligned} (2.13) \quad \nabla_{E_1} E_1 &= e^x E_2, & \nabla_{E_2} E_2 &= 0, & \nabla_{E_3} E_3 &= 0, \\ \nabla_{E_1} E_2 &= -e^x E_1 + e^{2x} E_3, & \nabla_{E_2} E_1 &= -e^{2x} E_3, & \nabla_{E_2} E_3 &= e^{2x} E_1, \\ \nabla_{E_1} E_3 &= -e^{2x} E_2, & \nabla_{E_3} E_1 &= -e^{2x} E_2, & \nabla_{E_3} E_2 &= e^{2x} E_1. \end{aligned}$$

Clearly  $(\phi, \xi, \eta, g)$  structure is an  $\alpha$ -Sasakian structure and satisfy,

$$(2.14) \quad (\nabla_X \phi)Y = \alpha(g(X, Y)\xi - \eta(Y)X), \quad \nabla_X \xi = -\alpha\phi X,$$

where  $\alpha = e^{2x} \neq 0$ . Hence  $(\phi, \xi, \eta, g)$  structure defines  $\alpha$ -Sasakian structure. Thus  $M$  equipped with  $\alpha$ -Sasakian structure is a  $\alpha$ -Sasakian manifold. The tangent vectors  $X$  and  $Y$  to  $M$  are expressed as linear combination of  $E_1, E_2, E_3$ , that is  $X = \sum_{i=1}^3 a_i E_i$  and  $Y = \sum_{i=1}^3 b_i E_i$ , where  $a_i$  and  $b_i (i = 1, 2, 3)$  are scalars.

On  $\alpha$ -Sasakian manifold  $(M, g)$ , we have

$$(2.15) \quad (\mathcal{L}_V g)(X, Y) = g(\nabla_X V, Y) + g(X, \nabla_Y V)$$

where  $\nabla$  denotes the Levi-Civita connection of  $M$ . Hence if  $(M, g)$  is a  $\eta$ -Ricci soliton with potential vector field  $V$ , then (1.2) and (2.15), we have

$$(2.16) \quad 2S(X, Y) = -g(\nabla_X V, Y) - g(X, \nabla_Y V) - 2\lambda g(X, Y) - 2\mu\eta\eta(X)\eta(Y).$$

By taking  $X = Y = e_i$  where  $e_i$  is an orthonormal basis and  $1 \leq i \leq n$ , then we have

$$(2.17) \quad \int_M [\operatorname{div} V + r + n\lambda + \mu] = 0.$$

On integrating the above equation we have by Green's theorem  $\int \operatorname{div} V = 0$  and for scalar curvature  $r$ , then we have

$$(2.18) \quad (r + n\lambda + \mu) \operatorname{Vol}(M) = 0.$$

The above equation implies that

$$(2.19) \quad r = -(n\lambda + \mu).$$

For Ricci solitons  $\mu = 0$ , then

$$(2.20) \quad \lambda = -\frac{r}{n}.$$

In  $\alpha$ -Sasakian manifolds scalar curvature  $r = \alpha^2(n-1)$ , we have

$$(2.21) \quad \lambda = -\frac{\alpha^2(n-1)}{n} < 0.$$

Hence, we state the following:

**Theorem 2.1.** A  $\eta$ -Ricci soliton in an  $\alpha$ -Sasakian is shrinking.

**Corollary 2.1.** If a metric  $g$  in an  $\alpha$ -Sasakian manifold is a  $\eta$ -Ricci soliton with  $V = \xi$  then it is  $\eta$ -Einstein.

**Proof.** Putting  $V = \xi$  in (1.2), then we have

$$(2.22) \quad (\mathcal{L}_\xi g)(X, Y) + 2S(X, Y) + 2\lambda g(X, Y) + 2\mu\eta(X)\eta(Y) = 0$$

where

$$(2.23) \quad (\mathcal{L}_\xi g)(X, Y) = g(\nabla_X \xi, Y) + g(X, \nabla_Y \xi) = 0$$

Substituting (2.23) in (2.22), then we get the result.

**Proposition 2.1.** If an  $\alpha$ -Sasakian manifold is a  $\eta$ -Ricci soliton with  $V$  point-wise collinear with  $\xi$ , then  $V$  is a constant multiple of  $\xi$  and the manifold is Einstein.

**Proof.**

$$(2.24) \quad (\mathcal{L}_\xi g)(X, Y) + 2S(X, Y) + 2\lambda g(X, Y) + 2\mu\eta(X)\eta(Y) = 0$$

where

$$(2.25) \quad (\mathcal{L}_V g)(X, Y) = g(\nabla_X V, Y) + g(X, \nabla_Y V).$$

Substituting (2.25) in (2.24), then we have

$$(2.26) \quad g(\nabla_X V, Y) + g(X, \nabla_Y V) + 2S(X, Y) + 2\lambda g(X, Y) + 2\mu\eta\eta(X)\eta(Y) = 0.$$

Putting  $V = a\xi$  in (2.26), we have

$$(2.27) \quad (Xa)\eta(Y) + (Ya)\eta(X) + 2S(X, Y) + 2\lambda g(X, Y) + 2\mu\eta\eta(X)\eta(Y) = 0.$$

Putting  $X = Y = \xi$  in (2.27), we have

$$(2.28) \quad (\xi a) + \alpha^2(n-1) + \lambda + \mu = 0.$$

Again putting  $X = \xi$  in (2.27), we have

$$(2.29) \quad (Ya) = [-\alpha^2(n-1) - \lambda - \mu]\eta(Y).$$

Equation (2.29) implies that

$$(2.30) \quad da = [-\alpha^2(n-1) - \lambda - \mu]\eta.$$

Applying  $d$  on both sides

$$(2.31) \quad d^2a = [-\alpha^2(n-1) - \lambda - \mu]d\eta.$$

Since  $d^2a = 0$  but  $d\eta$  is nowhere vanishing. Therefore,  $-\lambda - \alpha^2(n-1) - \mu = 0$  which implies  $da = 0$  that is,  $a$  is constant. On the above hence we state that

**Theorem 2.2.** On an  $\alpha$ -Sasakian manifold, the contact form  $\eta$  is closed if and only if  $\xi$  is integrable and the Nijenhuis tensor field of the structural endomorphism  $\phi$  vanishes identically.

**Proof.** From (2.4), we have

$$(2.32) \quad \begin{aligned} (d\eta)(X, Y) &= \frac{1}{2}[X(\eta(Y)) - Y(\eta(X)) - \eta([X, Y])] \\ &= \frac{1}{2}[g(Y, \nabla_X \xi) - g(X, \nabla_Y \xi)] = -\alpha g(\phi X, Y). \end{aligned}$$

If  $\xi$  is integrable then  $d\eta = 0$ .

Nijenhuis tensor field of the endomorphism is given by

$$(2.33) \quad \begin{aligned} N_\phi(X, Y) &= \phi^2[X, Y] + [\phi X, \phi Y] - \phi[\phi X, Y] - \phi[X, \phi Y] \\ &= \phi^2\{\nabla_X Y - \nabla_Y X\} + \{\nabla_{\phi X} \phi Y - \nabla_{\phi Y} \phi X\} \\ &- \phi\{\nabla_{\phi X} Y - \nabla_Y \phi X\} - \phi\{\nabla_X \phi Y - \nabla_{\phi Y} X\} = 0. \end{aligned}$$

### 3. Parallel symmetric second order tensors and Ricci Solitons in $\alpha$ -Sasakian manifolds

Fix  $h$  a symmetric tensor field of  $(0, 2)$ -type which we suppose to be parallel with respect to  $\nabla$  that is  $\nabla h = 0$ . Applying the Ricci identity [20]

$$(3.1) \quad \nabla^2 h(X, Y; Z, W) - \nabla^2 h(X, Y; W, Z) = 0,$$

we obtain the relation

$$(3.2) \quad h(R(X, Y)Z, W) + h(Z, R(X, Y)W) = 0.$$

Replacing  $Z = W = \xi$  in (3.2) and by using (2.5) and by the symmetry of  $h$ , we have

$$(3.3) \quad 2\alpha^2[\eta(Y)h(X, \xi) - \eta(X)h(Y, \xi)] = 0.$$

Put  $X = \xi$  in (3.3) and by virtue of (2.1), we have

$$(3.4) \quad 2\alpha^2[\eta(Y)h(\xi, \xi) - h(Y, \xi)] = 0.$$

Since  $\alpha^2 \neq 0$ , it results

$$(3.5) \quad h(Y, \xi) = \eta(Y)h(\xi, \xi).$$

Let us call a regular  $\alpha$ -Sasakian manifolds with  $\alpha^2 \neq 0$  and remark that  $\alpha$ -Sasakian manifold is regular, where regularity means the nonvanishing of the Ricci curvature with respect to the generator of  $\alpha$ -Sasakian manifolds.

**Definition 3.1.**  $\xi$  is called semi-torse forming vector field for  $\alpha$ -Sasakian manifold if, for all vector fields  $X$  :

$$(3.6) \quad R(X, \xi)\xi = 0.$$

From (2.5), we have  $R(X, \xi)\xi = \alpha^2[X - \eta(X)\xi]$  and therefore, if  $X \in \ker \xi = \xi^\perp$ , then  $R(X, \xi)\xi = \alpha^2 X$  and we obtain:

**Proposition 3.1.** For an  $\alpha$ -Sasakian manifold the following are equivalent:

- (1) is regular,
- (2)  $\xi$  is not semi-torse forming,
- (3)  $S(\xi, \xi) \neq 0$ , that is,  $\xi$  is non-degenerate with respect to  $S$ ,

Now, differentiating the equation (3.5) covariantly with respect to  $X$ , we have

$$(3.7) \quad \begin{aligned} (\nabla_X h)(Y, \xi) + h(\nabla_X Y, \xi) + h(Y, \nabla_X \xi) &= [(\nabla_X \eta)(Y) + \eta(\nabla_X Y)]h(\xi, \xi) \\ &+ \eta(Y)[(\nabla_X h)(Y, \xi) + 2h(\nabla_X \xi, \xi)]. \end{aligned}$$

By using the parallel condition  $\nabla h = 0$ ,  $\eta(\nabla_X \xi) = 0$  and (3.5) in (3.7), we have

$$(3.8) \quad h(Y, \nabla_X \xi) = (\nabla_X \eta)(Y)h(\xi, \xi).$$

By using (2.4) in (3.8), we get

$$(3.9) \quad -\alpha h(Y, \phi X) = \alpha g(X, \phi Y)h(\xi, \xi).$$

Replacing  $X = \phi X$  in (3.9), we get

$$(3.10) \quad \alpha[h(Y, X) - g(Y, X)h(\xi, \xi)] = 0.$$

Clearly  $\alpha$  is a nonzero smooth function in  $\alpha$ -Sasakian manifold this implies that

$$(3.11) \quad h(X, Y) = g(X, Y)h(\xi, \xi),$$

the above equation implies that  $h(\xi, \xi)$  is a constant, via (3.5). Now by considering the above condition we state the following theorem:

**Theorem 3.1.** A symmetric parallel second order covariant tensor in an  $\alpha$ -Sasakian manifold is a constant multiple of the metric tensor.

**Theorem 3.2.** Let  $M$  be a  $\alpha$ -Sasakian manifold, the symmetric  $(0, 2)$ -tensor field  $h := (\mathcal{L}_\xi g)(X, Y) + 2S(X, Y) + 2\mu\eta(X)\eta(Y)$  is parallel with respect to the Levi-Civita connection associated to  $g$ . Then  $(g, \xi, \lambda, \mu)$  yields an  $\eta$ -Ricci soliton.

**Proof.** Assume  $h(\xi, \xi) = (\mathcal{L}_\xi g)(\xi, \xi) + 2S(\xi, \xi) + 2\mu\eta(\xi)\eta(\xi)$ . Now (2.22), can be written in form

$$(3.12) \quad h(X, Y) = -2\lambda g(X, Y).$$

that is,

$$(3.13) \quad \lambda = \frac{-1}{2}h(\xi, \xi).$$

Therefore,  $(\mathcal{L}_\xi g)(\xi, \xi) + 2S(\xi, \xi) + 2\mu\eta(\xi)\eta(\xi) = -2\lambda g(\xi, \xi)$ .

If  $\mu = 0$ , then  $(\mathcal{L}_\xi g)(\xi, \xi) + 2S(\xi, \xi) = -2\lambda g(\xi, \xi)$ . Hence we conclude that

**Corollary 3.1.** On a  $\alpha$ -Sasakian manifold the symmetric  $(0, 2)$ -tensor field  $h := (\mathcal{L}_\xi g)(\xi, \xi) + 2S(\xi, \xi)$  is parallel with respect to the Levi-Civita connection associated to  $g$ , then the  $\eta$ -Ricci soliton relation defines a Ricci soliton on  $M$ .

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